A Dual-Augmented Block Minimization Framework for Learning with Limited Memory

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Abstract

- ▶ In this work, we consider **Empirical Risk Minimization (ERM)** when data size is larger than the memory capacity of machines.
- ► State-of-the-art batch algorithms become slow due to I/O.
- ► Online algorithms converge slowly (especially for non-smooth regularizer), while existing distributed approach requires data to fit into memory of several machines.
- ▶ We propose a **Block Minimization** framework that generalizes (Yu. et al. 2010) for SVM to that for any convex ERM, which can be integrated with **any convex optimization solver** to achieve global fast convergence in limited-memory condition.

Regularized Empirical Risk Minimization (ERM)

Given a data set $\mathcal{D} = \{(\Phi_n, \mathbf{y}_n)\}_{n=1}^N$, the ERM estimates model through

$$\min_{\boldsymbol{w} \in \mathbb{R}^d} F(\boldsymbol{w}) = R(\boldsymbol{w}) + \sum_{n=1}^N L_n(\Phi_n \boldsymbol{w})$$
 (1)

▶ $\mathbf{w} \in \mathbb{R}^d$ are parameters to be estimated, Φ_n is $p \times d$ feature matrix of n-th sample, and $L_n(.)$, R(.) are loss function and regularizer.

Examples

- ▶ Multiclass Classification: $(p = |\mathcal{Y}|, \text{ where } \mathcal{Y}: \text{label set}).$
- Logistic loss: $L_n(\xi) = \log(\sum_{k \in \mathcal{Y}} \exp(\xi_k)) \xi_{y_n}$. Hinge loss: $L_n(\xi) = \max_{k \in \mathcal{Y}} (1 - \delta_{k,y_n} + \xi_k - \xi_{y_n})$.
- ▶ Multitask Regression: (p = K, where K = #tasks)
- Square loss: $L_n(\xi) = \frac{1}{2} ||\xi y_n||^2$.
- ▶ Others: Ranking, Matrix Completion, Structured Learning, Clustering etc...
- ► **Regularizers**: L2 norm $\lambda \| \mathbf{w} \|^2$, L1 norm $\lambda \| \mathbf{w} \|_1$, Group norm $\lambda \| \mathbf{W} \|_{\mathcal{G}}$, Nuclear norm $\lambda \| \mathbf{W} \|_*$, and etc.

Strong Convexity & Smoothness

A function f(x) is **strongly convex** iff it is lower bounded by a simple quadratic function

$$f(\mathbf{y}) \ge f(\mathbf{x}) + \nabla f(\mathbf{x})^T (\mathbf{y} - \mathbf{x}) + \frac{m}{2} ||\mathbf{x} - \mathbf{y}||^2$$
 (2)

for some constant m > 0 and $\forall x, y \in dom(f)$.

A function f(x) is **smooth** iff it is upper bounded by a simple quadratic function

$$f(\mathbf{y}) \leq f(\mathbf{x}) + \nabla f(\mathbf{x})^{T} (\mathbf{y} - \mathbf{x}) + \frac{M}{2} ||\mathbf{x} - \mathbf{y}||^{2}$$
(3)

for some constant $0 \le M < \infty$ and $\forall x, y \in dom(\overline{f})$.

▶ **Theorem 1:** A convex function f(.) is smooth with parameter M if and only if its convex conjugate $f^*(.)$ is strongly convex with parameter m = 1/M.

Dual Form

The dual of ERM problem (1) is of the form

$$\min_{\alpha_n \in \mathbb{R}^p} G(\alpha) = R^*(-\sum_{n=1}^N \Phi_n^T \alpha_n) + \sum_{n=1}^N L_n^*(\alpha_n). \tag{4}$$

- ▶ Block Coordinate Descent on (4) guarantees convergence only for **smooth** $R^*(.)$ (**strongly convex** R(.)), which does not hold for most of regularizers.
- ▶ Use **Proximal Minimization** to ensure convergence for any convex ERM.

Dual-Augmented Block Minimization

► The Dual-Augmented Lagrangian method (or equivalently, Primal Proximal Minimization) solves a series of **augmented sub-problems**

$$\hat{\boldsymbol{w}}^{t+1} = \underset{\boldsymbol{w}}{arg \min} F(\boldsymbol{w}) + \frac{1}{2\eta_t} \|\boldsymbol{w} - \hat{\boldsymbol{w}}^t\|^2,$$
 (5)

which, by Theorem 1, has a dual problem of **smooth** $\tilde{R}^*(.)$ since the augmented regularizer $\tilde{R}(\mathbf{w})$ is **strongly convex**.

Let $\mathcal{L}(\mathbf{w}, \alpha)$ be the Lagrangian of (5). Our algorithm performs **Block-Coordinate Descent** on dual of (5), which minimizes block of variables α_B via

$$\max_{\alpha_B} \min_{\mathbf{w}} \mathcal{L}(\mathbf{w}, \alpha) = \min_{\mathbf{w}} \max_{\alpha_B} \mathcal{L}(\mathbf{w}, \alpha)$$

$$= \min_{\mathbf{w}} R(\mathbf{w}) + \sum_{n \in B} L_n(\Phi_n \mathbf{w}) + \mu_{\bar{B}}^T \mathbf{w} + \frac{1}{2\eta_t} \|\mathbf{w} - \hat{\mathbf{w}}_t\|^2,$$
(6)

which requires only data in block B and can be solved via **any solver designed** for (1), where vector $\mu_{\bar{B}}$ memorizes historical gradient given by data not in B:

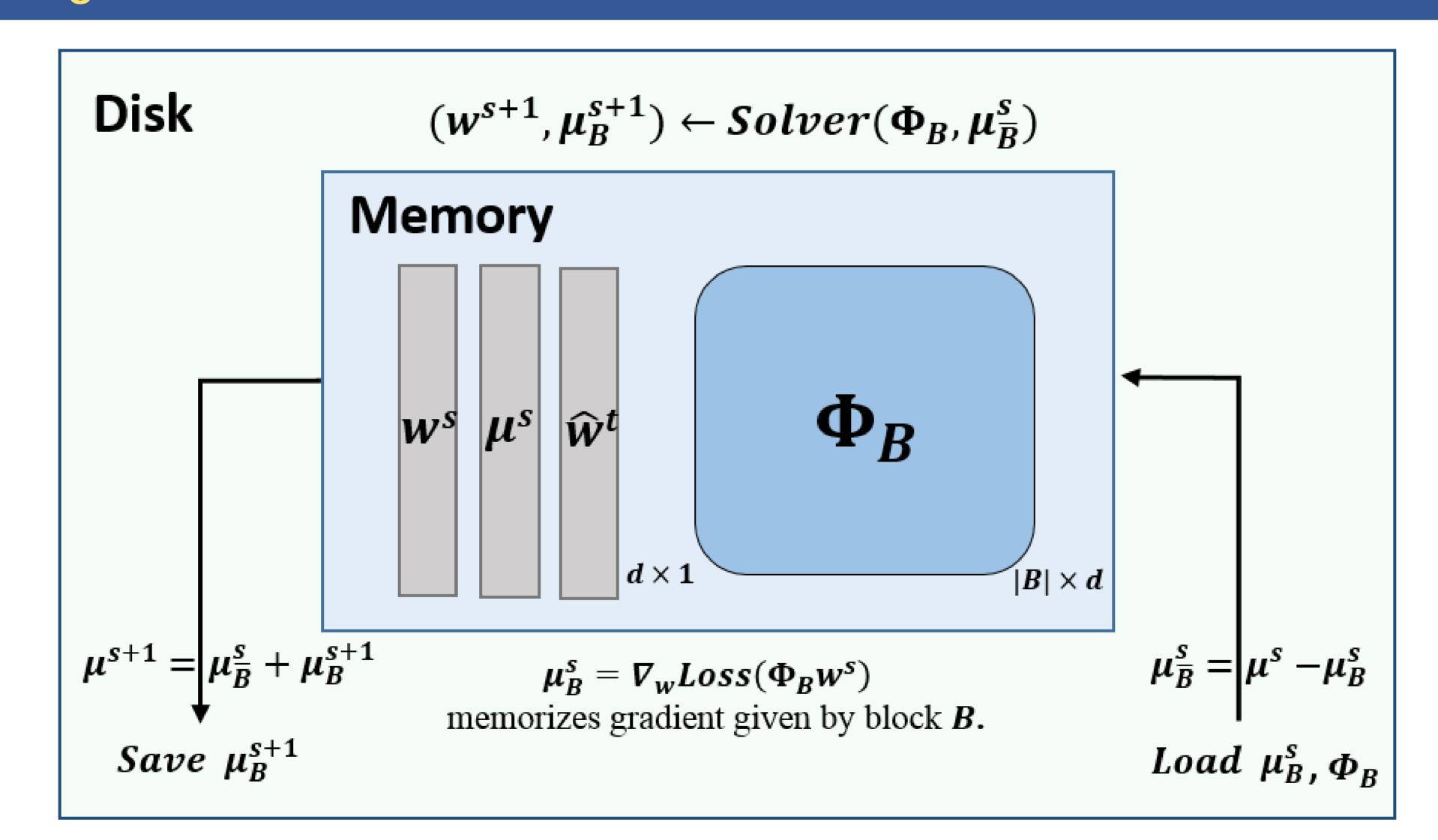
$$\mu_{\bar{B}} = \sum_{n \notin B} \Phi_n^T \alpha_n = \sum_{n=1}^N \Phi_n^T \alpha_n - \sum_{n \in B} \Phi_n^T \alpha_n = \mu - \mu_B$$
 (7)

▶ After solving block sub-problem (6), we obtain new α_B^* and μ_B^* via

$$\alpha_B^* = \nabla_{\xi_B} Loss(\xi_B^* = \Phi_B \mathbf{w}^*)$$
 $\mu_B^* = \Phi_B^T \alpha_B^* = \nabla_{\mathbf{w}} Loss(\Phi_B \mathbf{w}^*).$ (8)

▶ Only one of α_B or μ_B needs to be maintained. If d > |B|p, maintaining α_B is cheaper; otherwise, maintaining μ_B is more space-efficient.

Algorithmic Framework



Dual-Augmented Block Minimization Algorithm

- 1. Split data \mathcal{D} into blocks $B_1, B_2, ..., B_K$.
- 2. Initialize $\hat{\boldsymbol{w}}^0 = \boldsymbol{0}, \, \boldsymbol{\mu}^0 = \boldsymbol{0}.$

for t = 0, 1, ... (outer iteration) do

for s = 0, 1, ..., S do

- 3.1.1. Draw B uniformly from $B_1, B_2, ..., B_K$.
- 3.1.2. Load \mathcal{D}_B , μ_B^s (or α_B^s) into memory.
- 3.1.3. Solve (6) to obtain **w***.
- 3.1.4. Maintain μ_B^{s+1} (or α_B^{s+1}) through relation (8).
- 3.1.5. Maintain $\mu^{s+1} = \mu_B^s + \mu_B^{s+1}$.
- 3.1.6. Save μ_B^{s+1} (or α_B^{s+1}) out of memory.

end for

3.2. $\hat{\mathbf{w}}^{t+1} = \mathbf{w}^*(\alpha^S)$.

end for

Convergence of Block Minimization

► The dual of (5) takes the form

$$\min_{\alpha_n \in \mathbb{R}^p} \tilde{R}^* (-\sum_{n=1}^N \Phi_n^T \alpha_n) + \sum_{n=1}^N L_n^* (\alpha_n)$$
 (9)

where $\tilde{R}^*(.)$ is the convex conjugate of $\tilde{R}(\mathbf{w}) = R(\mathbf{w}) + \frac{1}{2n_t} ||\mathbf{w} - \mathbf{w}_t||^2$.

- Since $\tilde{R}(\mathbf{w})$ is **strongly convex** with parameter $m = 1/\eta_t$, the convex conjugate $\tilde{R}^*(.)$ is **smooth** with parameter $M = \eta_t$ according to Theorem 1.
- The augmented dual (9) is composite of a **convex**, **smooth** function plus a **convex**, **block-separable** function, for which BCD has guaranteed convergence to optimum. In particular, with probability 1ρ

$$\tilde{F}^*(lpha^s) - \tilde{F}^* \le \epsilon$$
, for $s \ge \beta K \log(\frac{\tilde{F}^*(lpha^0) - \tilde{F}^*}{\rho \epsilon})$ (10)

for some constant $\beta > 0$ if (i) $L_n(.)$ is smooth, or (ii) $L_n(.)$ is polyhedral and R(.) is also polyhedral or smooth. Otherwise, for any convex $L_n(.)$, R(.),

$$\tilde{F}^*(\alpha^s) - \tilde{F}^* \le \epsilon$$
, for $s \ge \frac{cK}{\epsilon} \log(\frac{\tilde{F}^*(\alpha^0) - \tilde{F}^*}{\rho \epsilon})$, (11)

with some constant c > 0 and probability $1 - \rho$.

Convergence of Overall Procedure

▶ The sequence $\{\hat{\boldsymbol{w}}^t\}_{t=1}^{\infty}$ produced by Proximal Minimization (5) with $\eta_t = \eta$ and radius of initial level set \mathcal{R} has

$$F(\hat{\boldsymbol{w}}^{t+1}) - F \leq \epsilon$$
, for $t \geq \tau \log(\frac{\omega}{\epsilon})$. (12)

for some constant $\tau, \omega > 0$ if both $L_n(.)$ and R(.) are (i) strictly convex and smooth or (ii) polyhedral. Otherwise, for any convex $F(\mathbf{w})$ we have

$$F(\hat{\mathbf{w}}^{t+1}) - F \le \mathcal{R}^2/(2\eta t).$$
 (13)

- Due to non-expansiveness of proximal operator, we show that solving sub-problem (5) with tolerance ϵ/t suffices for convergence to ϵ overall precision where t is the number of outer iterations required by (12), (13).
- ► The **overall procedure** requires $O(K \log(1/\epsilon) \log(t/\epsilon)) = O(K \log^2(1/\epsilon))$ block minimization steps if $L_n(.)$, R(.) are **strictly convex and smooth, or polyhedral**. Otherwise, we need $O(K(1/\epsilon) \log(t/\epsilon)) = O(\frac{K}{\epsilon} \log(1/\epsilon))$ block minimization steps as long as $L_n(.)$ is **smooth**.

Experiments

Data	#train	#test	dimension	#non-zeros	Memory (GB)	Block
webspam	315,000	31,500	680,714	1,174,704,031	20.7	2.07
rcv1	202,420	20,242	7,951,176	656,977,694	12.0	2.20
year-pred	463,715	51,630	2,000	927,893,715	13.7	1.38
E2006	16,087	3,308	30,000	8,088,636	8.08	0.80

